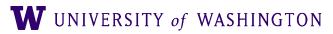
Transformers, I

LING 575K Deep Learning for NLP Shane Steinert-Threlkeld April 27 2022







Announcements

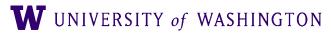
- Shapes, shapes, shapes:
 - In your code, annotate the shape that each Tensor should have (see e.g. `forward` in hw3/ref/word2vec.py)
 - If you get a shape error, print out the shape of each Tensor
 - These are the most common issues and biggest pain point in ML land
- HW4: use floating-point numbers for bag-of-words counts, e.g.
 - NOT [1, 0, 0, 3], but [1.0, 0.0, 0.0, 3.0]
- Patas: should be back, but also safe to just keep using dryas





Today's Plan

- Attention
- Limitations of Recurrent Models
- Transformers: building blocks
 - Self-attention
 - Encoder architecture







Limitations of Recurrent Models





- This has at least two issues:
 - Creates "long path lengths" between sequence positions
 - Not parallelizable

RNNs Unrolling

• Recall: RNNs are "unrolled" across time, same operation at each step

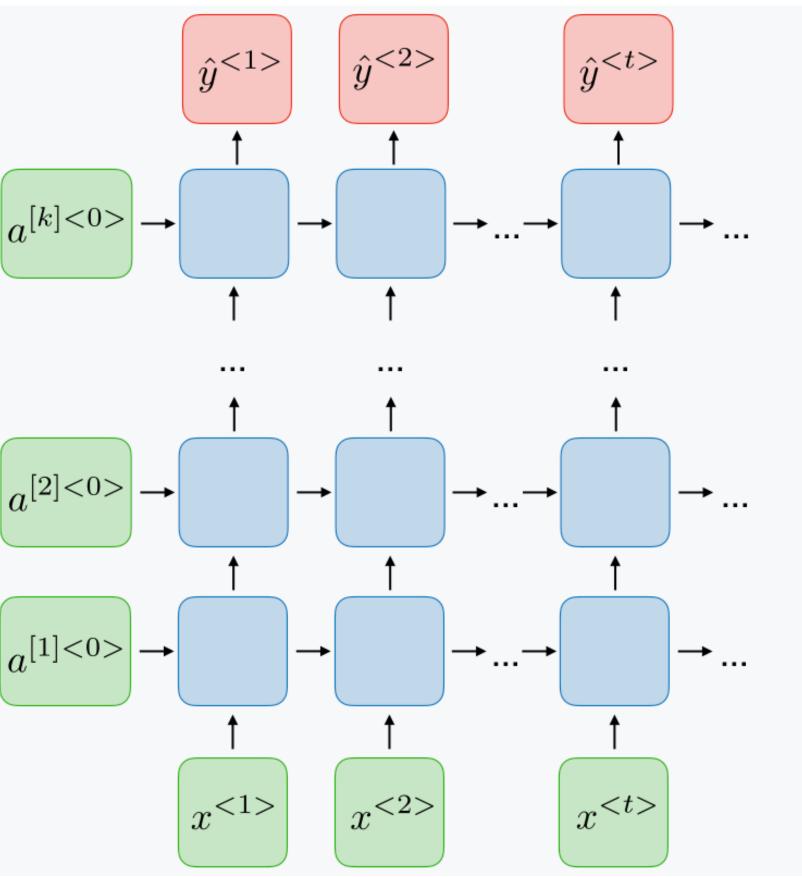




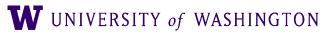


Long Path Lengths

- Gating mechanisms help **RNNs** learn long distance dependencies, by alleviating the vanishing gradient problem
- But: still takes a linear number of computations for one token to influence another
 - Long-distance dependencies are still hard!



Students who ... enjoy

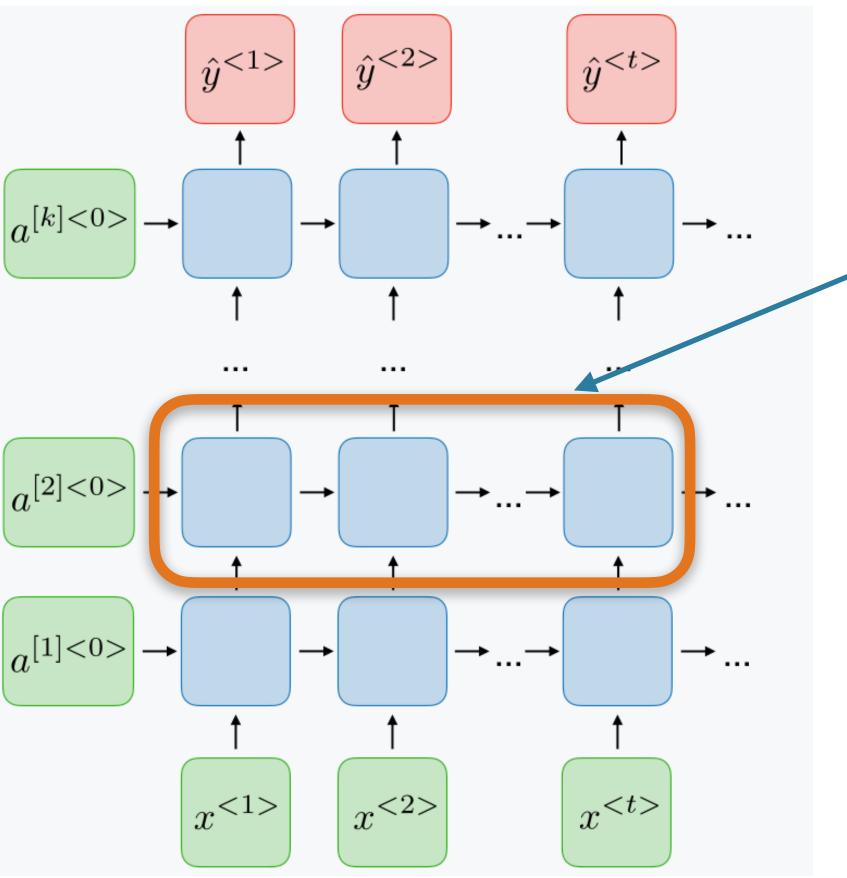






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Linear "path length" for interaction between tokens

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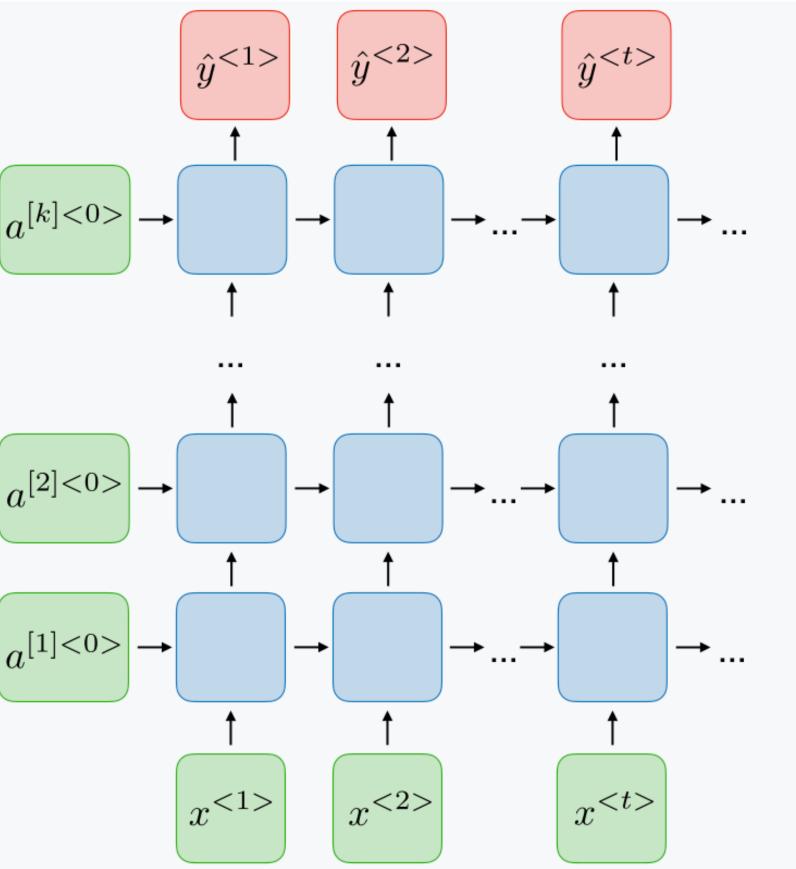




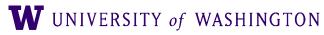
Lack of Parallelizability

- Modern hardware (e.g. GPUs) are very good at doing independent computations in parallel
- RNNs are inherently serial:
 - Cannot compute future time steps without the past
- Bottleneck that makes scaling up difficult





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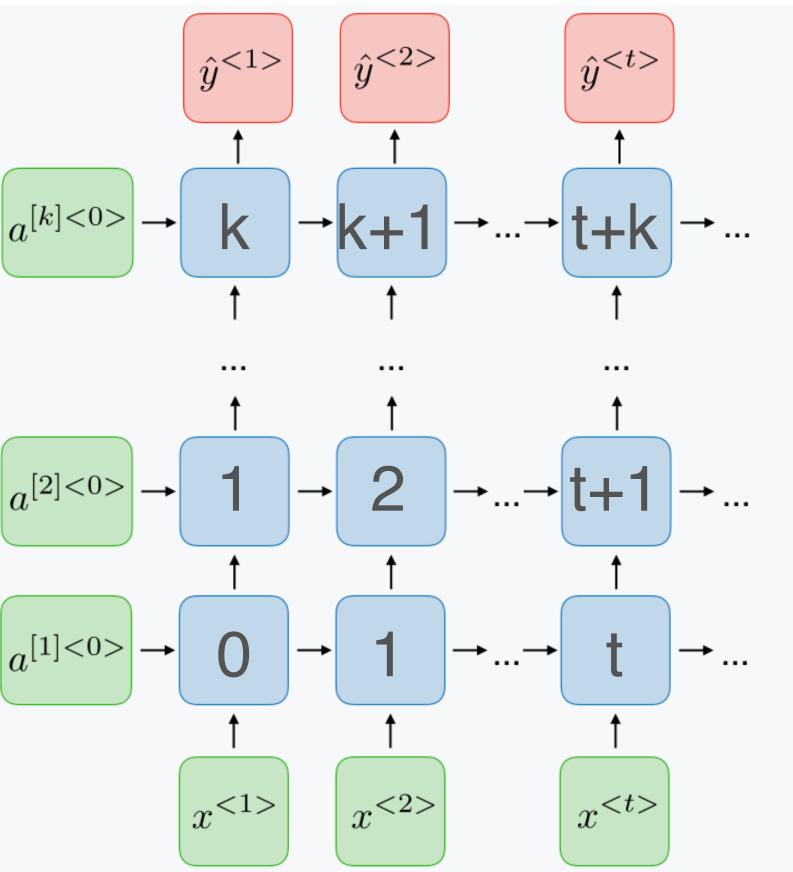




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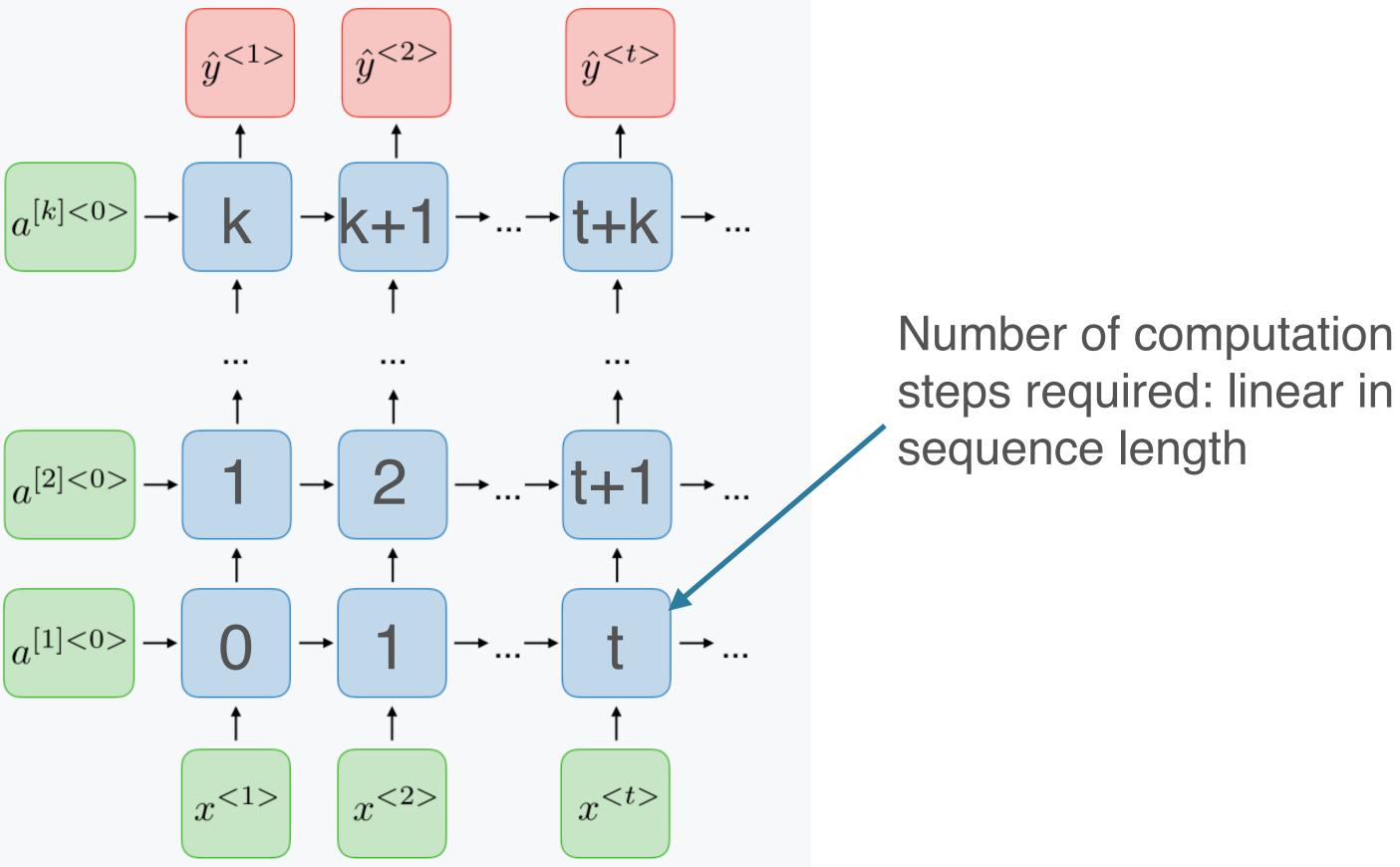
Students who ... enjoy





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Transformer Architecture





Attention Is All You Need

Ashish Vaswani* Google Brain avaswani@google.com

Noam Shazeer* Google Brain noam@google.com

Llion Jones* Google Research llion@google.com

Aidan N. Gomez^{*}[†] Łukasz Kaiser* University of Toronto Google Brain aidan@cs.toronto.edu lukaszkaiser@google.com

Illia Polosukhin* [‡] illia.polosukhin@gmail.com

The dominant sequence transduction models are based on complex recurrent or convolutional neural networks that include an encoder and a decoder. The best performing models also connect the encoder and decoder through an attention mechanism. We propose a new simple network architecture, the Transformer, based solely on attention mechanisms, dispensing with recurrence and convolutions entirely. Experiments on two machine translation tasks show these models to be superior in quality while being more parallelizable and requiring significantly less time to train. Our model achieves 28.4 BLEU on the WMT 2014 Englishto-German translation task, improving over the existing best results, including ensembles, by over 2 BLEU. On the WMT 2014 English-to-French translation task, our model establishes a new single-model state-of-the-art BLEU score of 41.0 after training for 3.5 days on eight GPUs, a small fraction of the training costs of the best models from the literature.

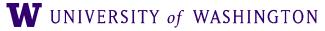
Niki Parmar* Google Research nikip@google.com

Jakob Uszkoreit* Google Research usz@google.com

Abstract

Paper link

(but see <u>Annotated</u> and <u>Illustrated</u> Transformer)







Key Idea

- Recurrence: not parallelizable, long "path lengths"
- Attention:
 - Parallelizable, short path lengths
- Transformer: "replace" recurrence with attention mechanism
 - Subtle issues in making this work, which we we will see

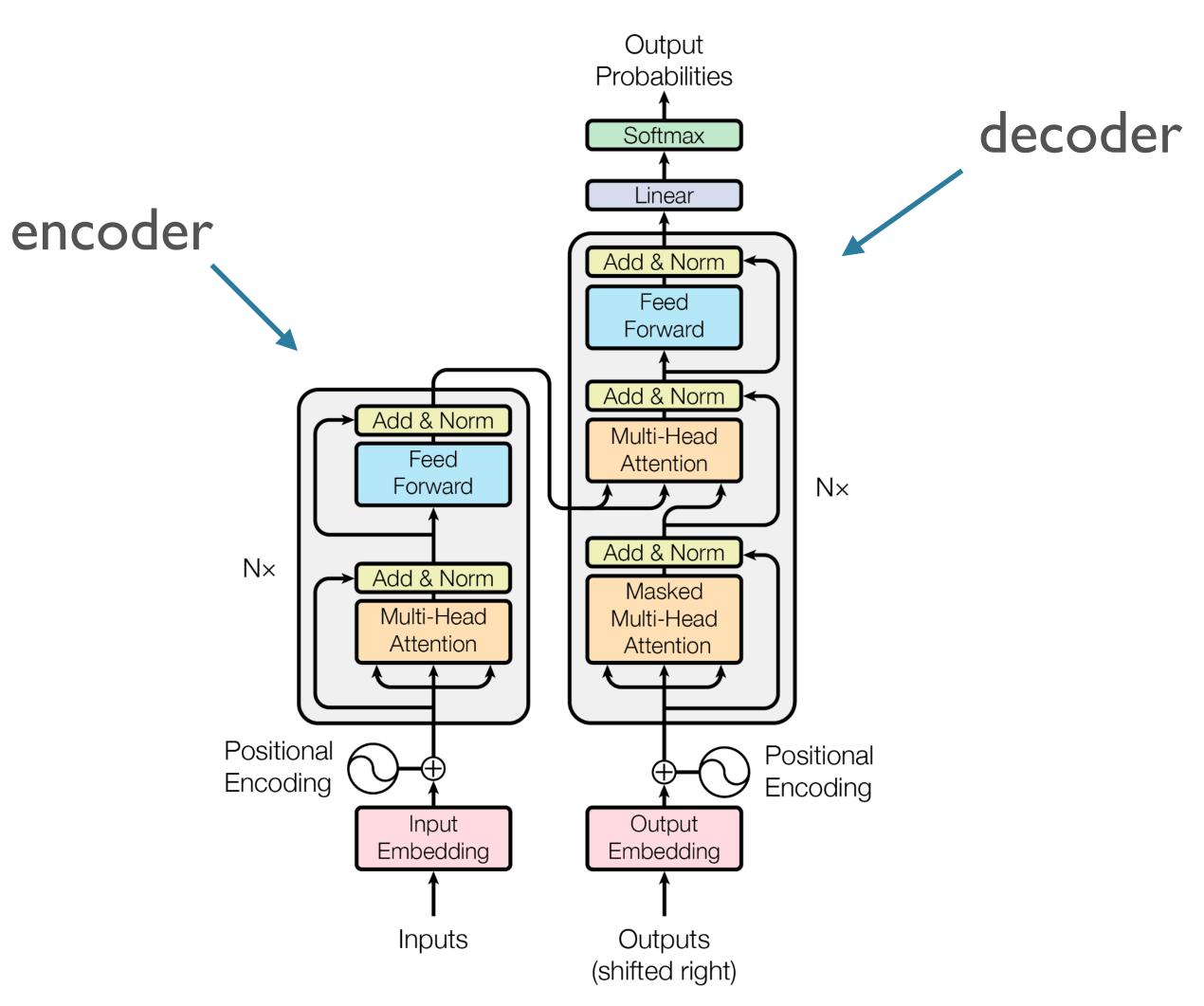










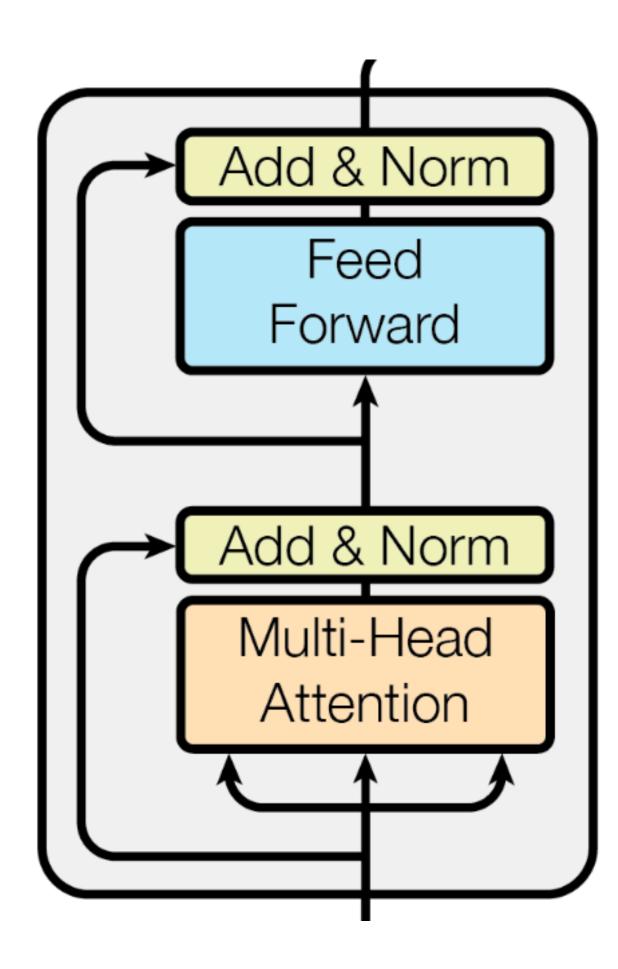


Full Model

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Transformer Block



N×

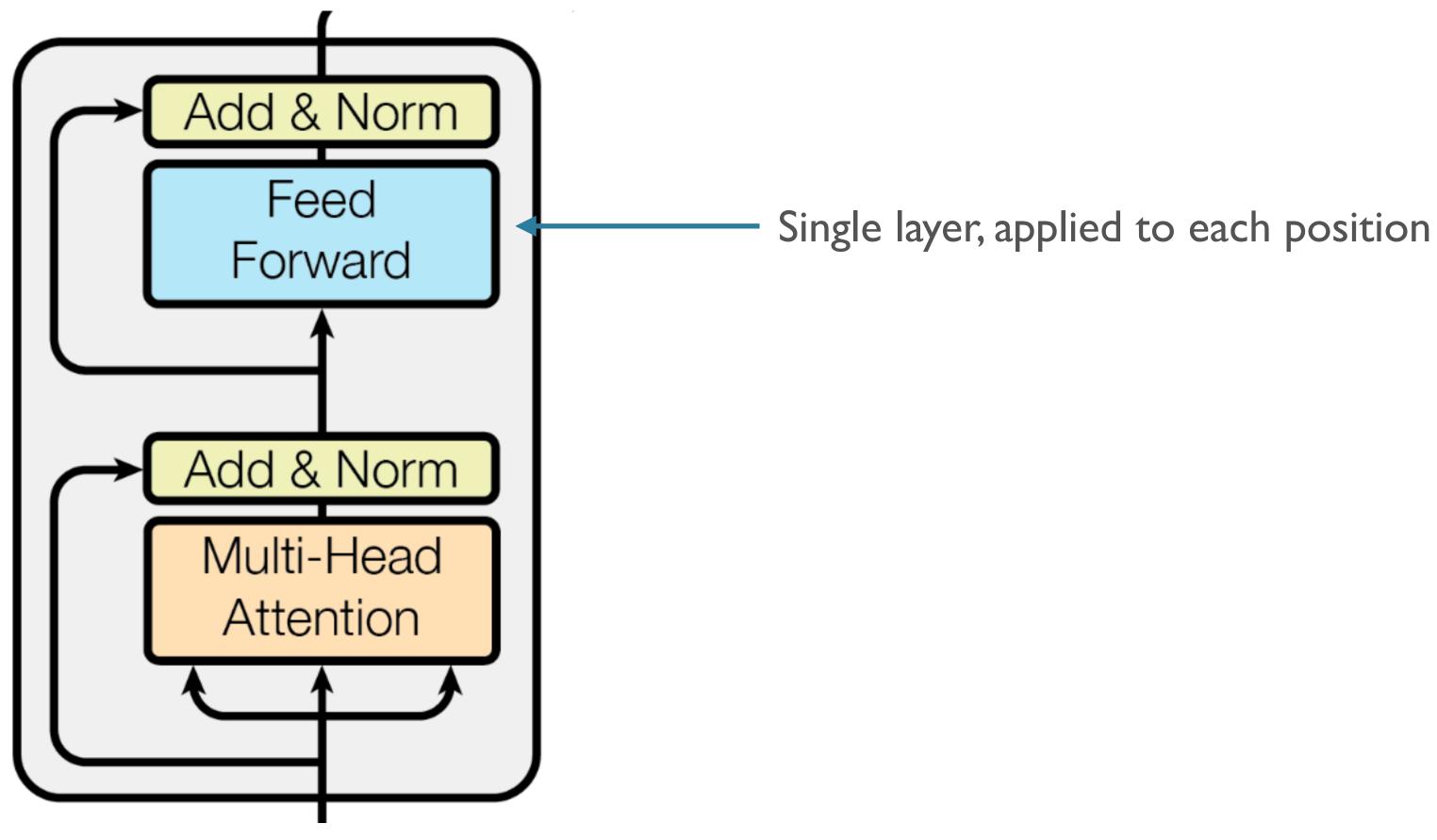
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Transformer Block



N×

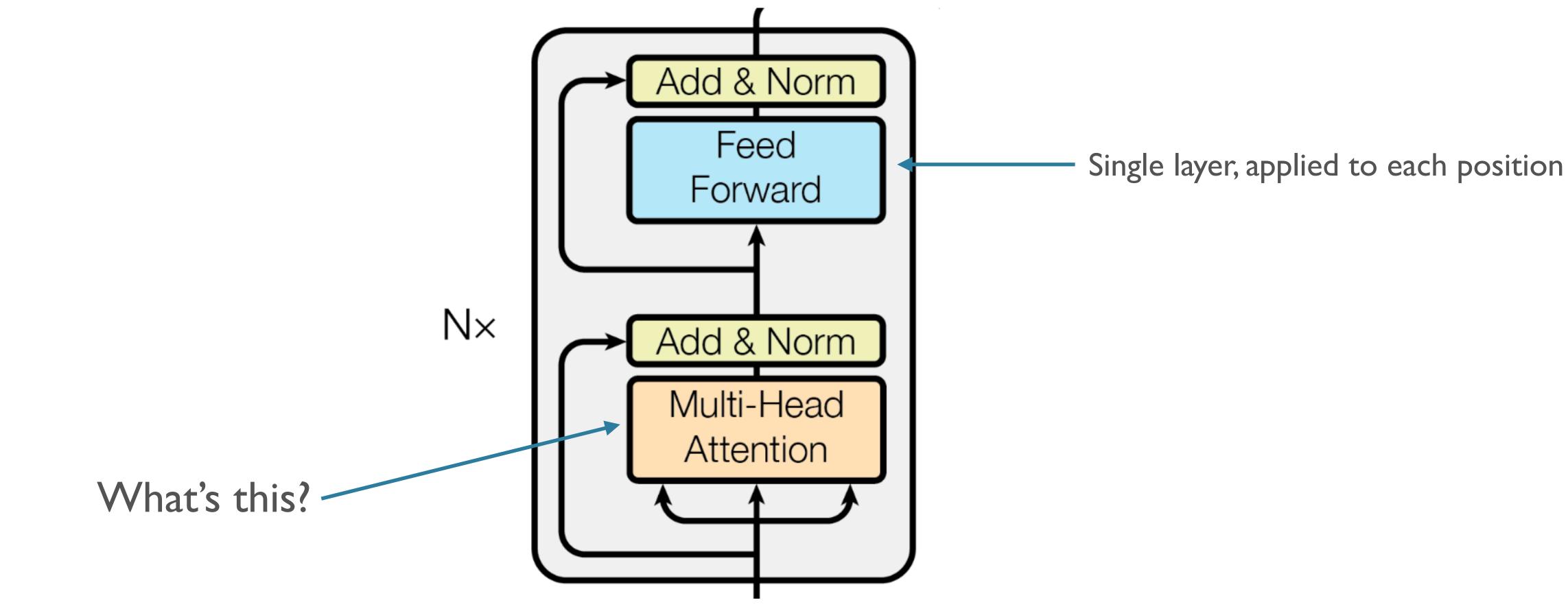












Transformer Block









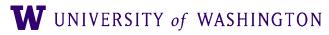
Scaled Dot-Product Attention



- Putting it together: Attent (keys/values in matrices)
- Stacking *multiple* queries: Attent (and scaling)

$$\operatorname{tion}(q, K, V) = \sum_{j} \frac{e^{q \cdot k_{j}}}{\sum_{i} e^{q \cdot k_{i}}} v_{j}$$

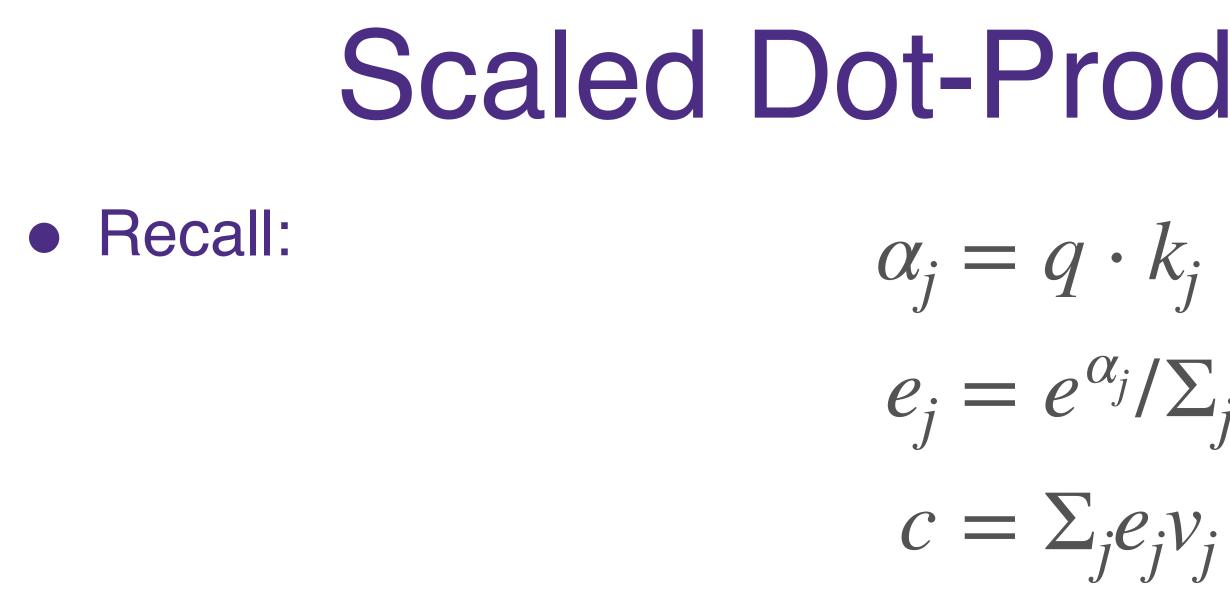
$$\operatorname{cion}(Q, K, V) = \operatorname{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$











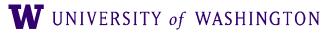
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Scaled Dot-Product Attention

 $e_j = e^{\alpha_j} / \sum_j e^{\alpha_j}$

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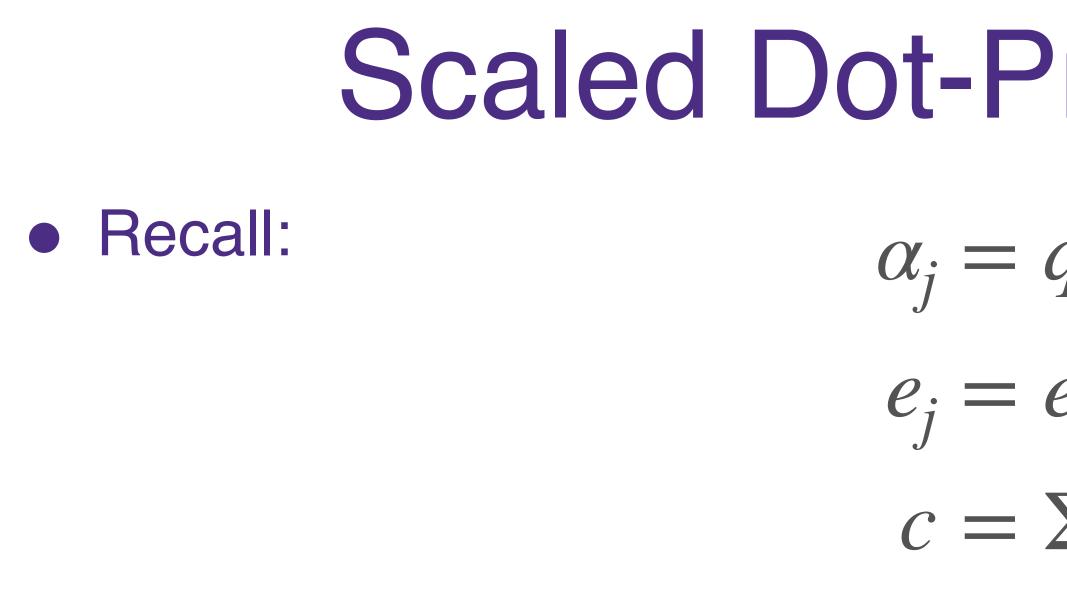
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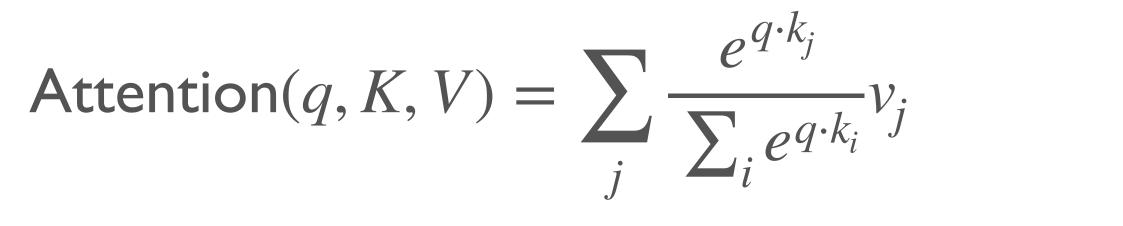
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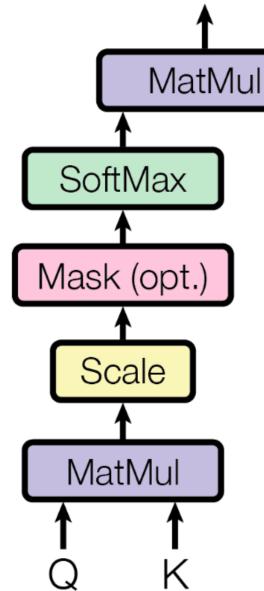
Scaled Dot-Product Attention

$$q \cdot k_j$$

$$e^{\alpha_j}/\sum_j e^{\alpha_j}$$

$$\Sigma_j e_j v_j$$





$$\operatorname{cion}(Q, K, V) = \operatorname{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$















• seq2seq: single decoder token attends to all encoder states







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- Transformer: *self*-attention
 - Every (token) position attends to every other position [including self!]
 - Caveat: in the encoder, and only by default
 - Mask in decoder to attend only to previous positions [next time]
 - Used for generation [NMT, LM, etc]







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- So vector at each position is a query
 - And a key, and a value
 - Linearly transformed, to be different "views"

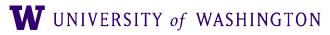






Self-Attention, Details

- Every token attends to every other token
- X: [seq_len, embedding_dim]
 - XW_q : queries
 - XW_k : keys
 - XW_{v} : values
 - Each W is [embedding_dim, embedding_dim] learned matrix

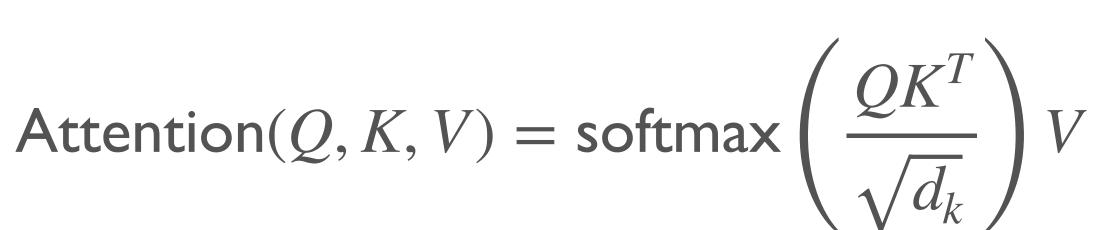






- $Q = XW_q$, $K = XW_k$, $V = XW_v$
 - K^T : [embedding_dim, seq_len]
 - QK^T : [seq_len, seq_len]
 - Dot-product of rows of Q with columns of K • $(QK^T)_{ii} = q_i \cdot k_i$
- Scaled by sq-rt of hidden dimension [see paper for motivation]
- Softmax: along *rows*, gets the weights











Self-Attention: Details

- Softmax output: each row has weights
 - How much q_i should pay attention to each v_j
- Matrix multiplication with V: output is [seq_len, embedding_dim]
 - Each row: weighted average of the v_i (rows of V)
 - Each row: the weight sum attention value for each query (each input token)
- [NB: a more explicit notation, if you like: <u>https://namedtensor.github.io/</u>]

Attention(Q, K, V) = softmax $\left(\frac{QK^T}{\sqrt{d_k}}\right)V$







Multi-headed Attention

- So far: a *single* attention mechanism.
- Could be a bottleneck: need to pay attention to different vectors for different reasons
- Multi-headed: several attention mechanisms in parallel

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MultiHead $(Q, K, V) = Concat(head_1, ..., head_h)W^O$ where head_i = Attention (QW_i^Q, KW_i^K, VW_i^V)



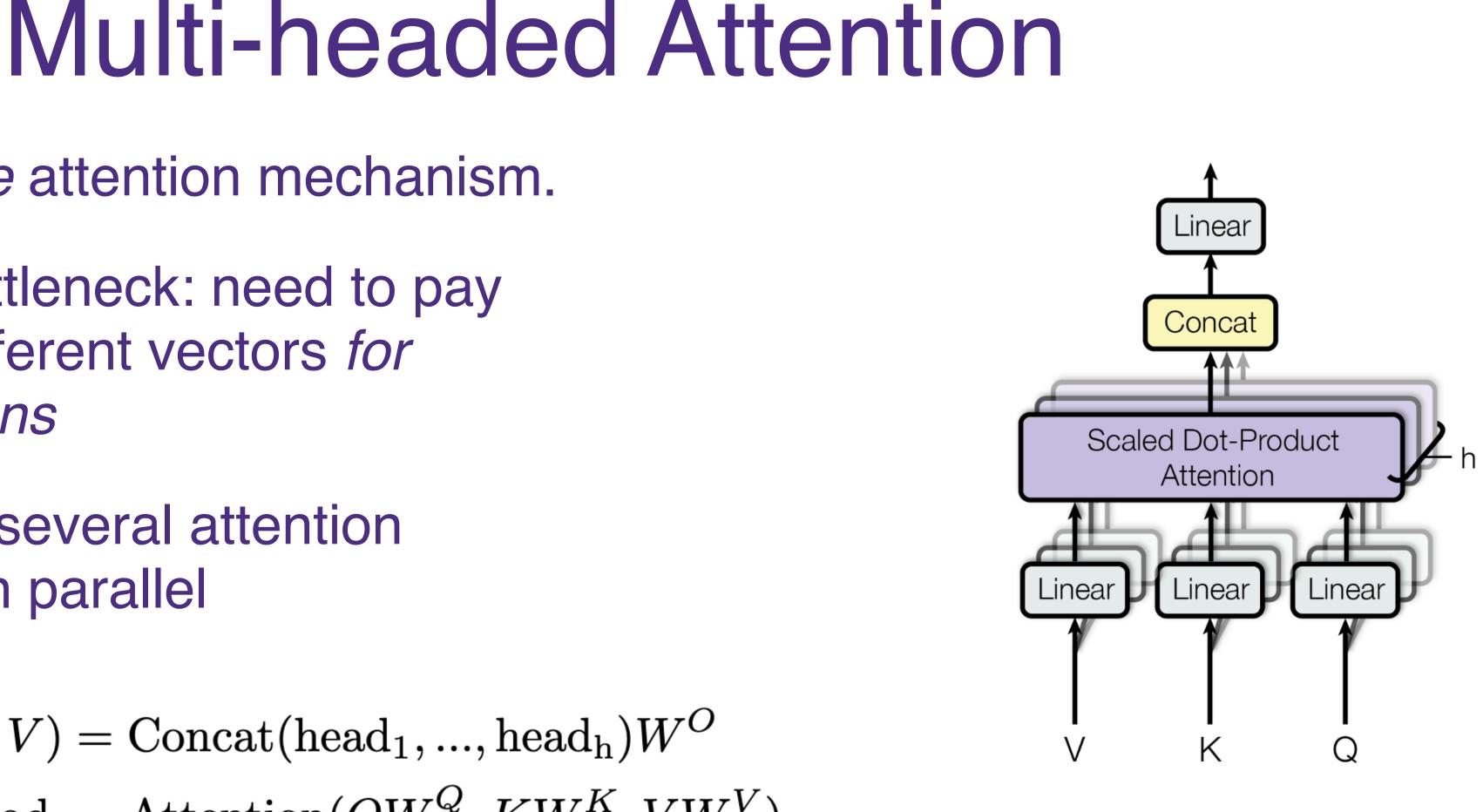






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Problem With Self-Attention

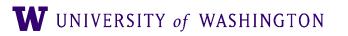
- Attention is order-independent
 - If we shuffle Q, K, V, we get the same output!







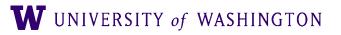








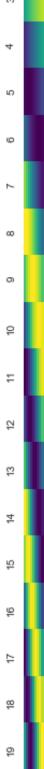
• Represented via *positional* encodings.

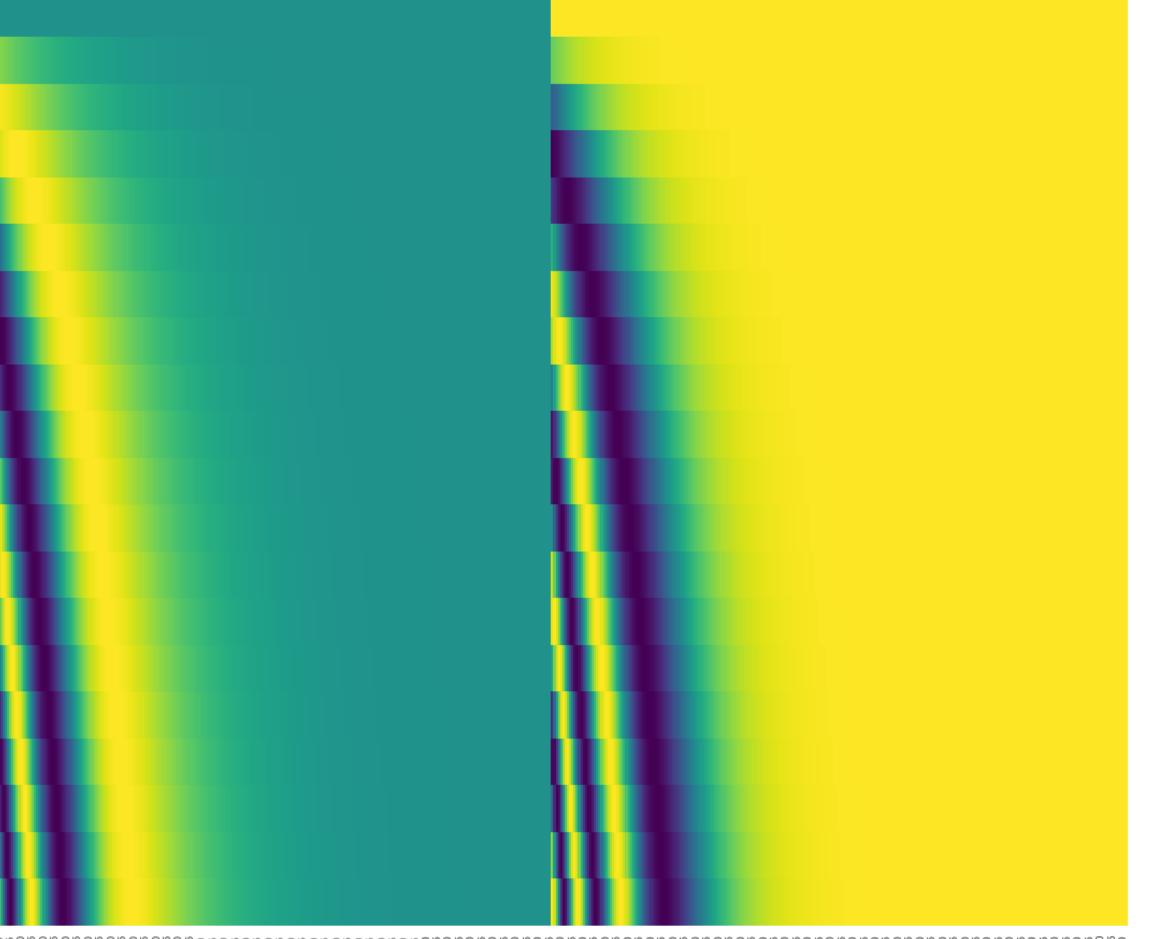






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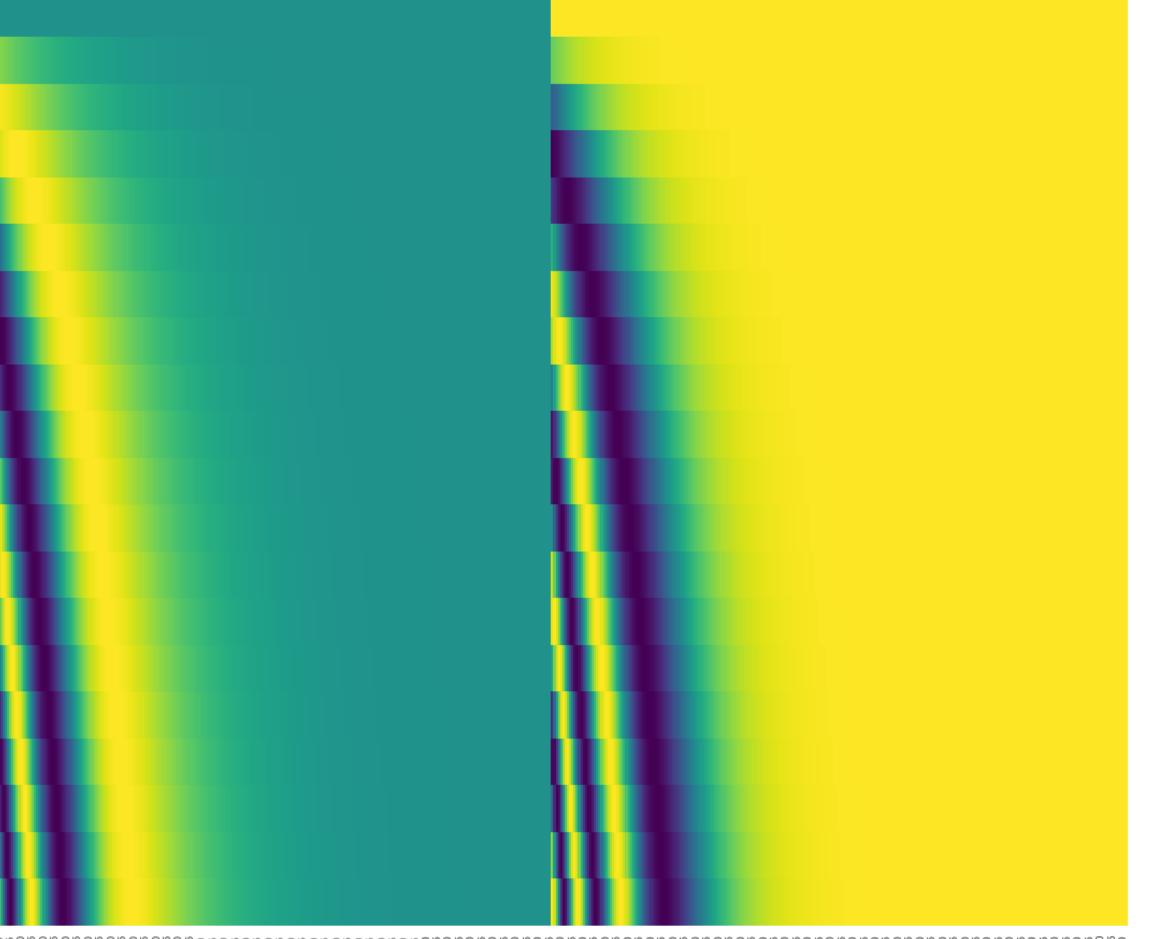








- Represented via *positional* encodings.
- *P*: [seq_len, embedding_dim]





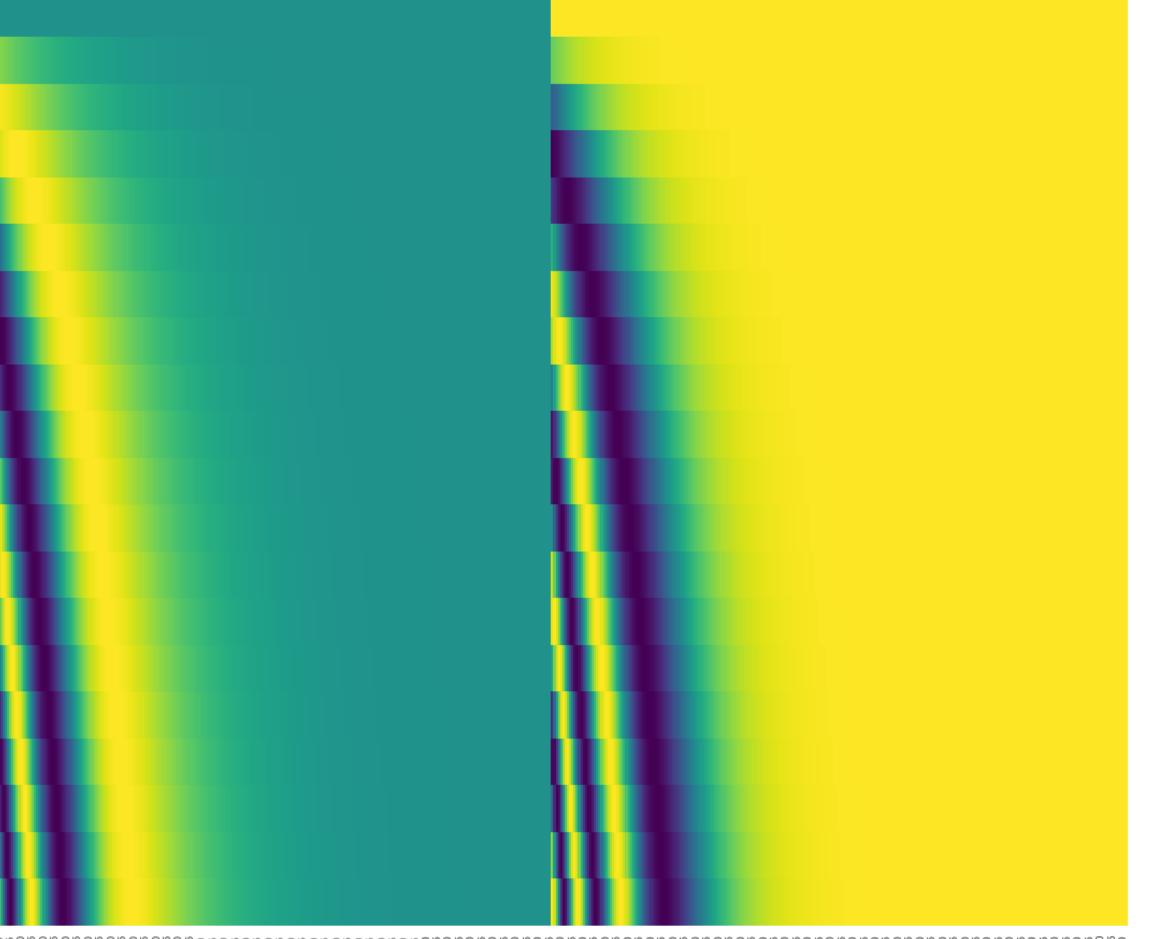








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 - Each row *i* represents that position in the sequence



 $\begin{array}{c} 0 & 0 \\ 0 & 0$





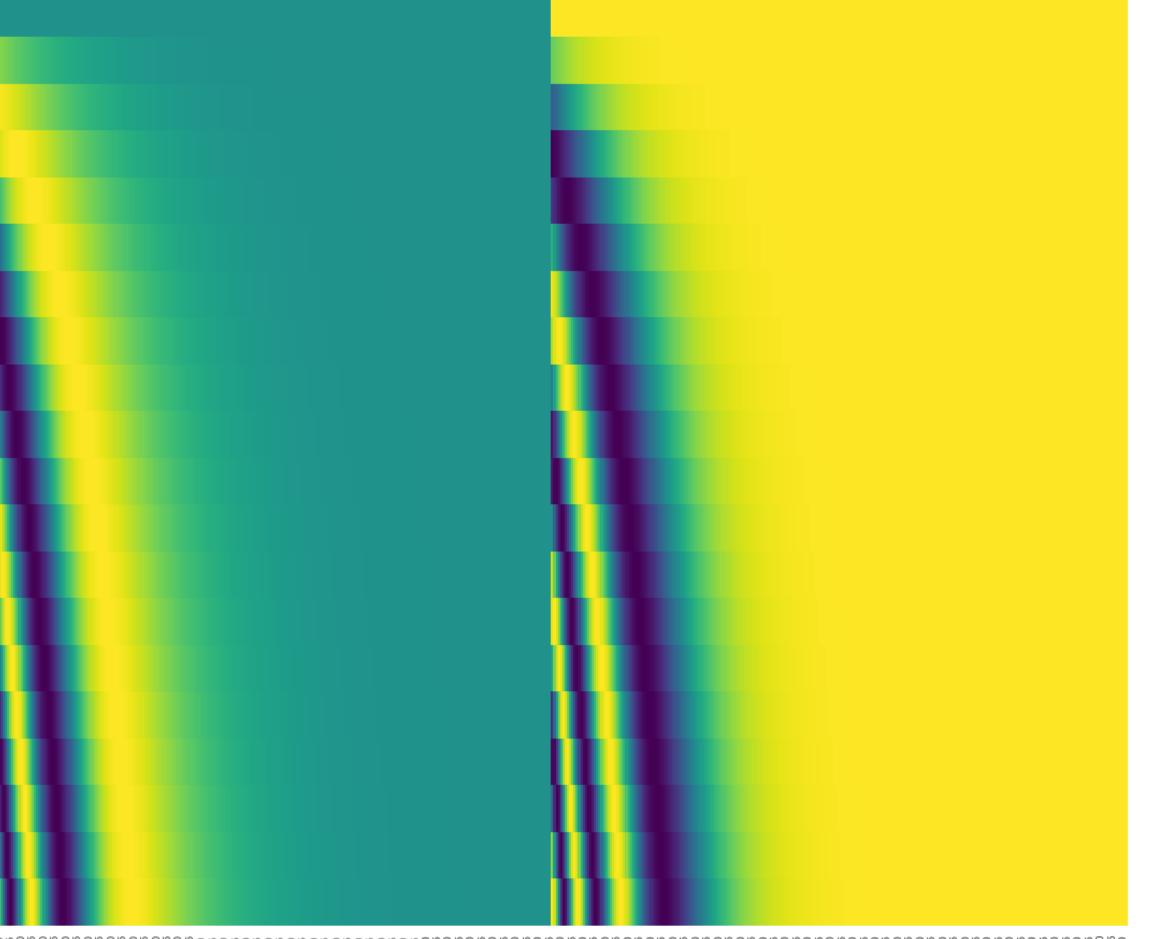






Representing Order

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 - Add to word embeddings at input layer:



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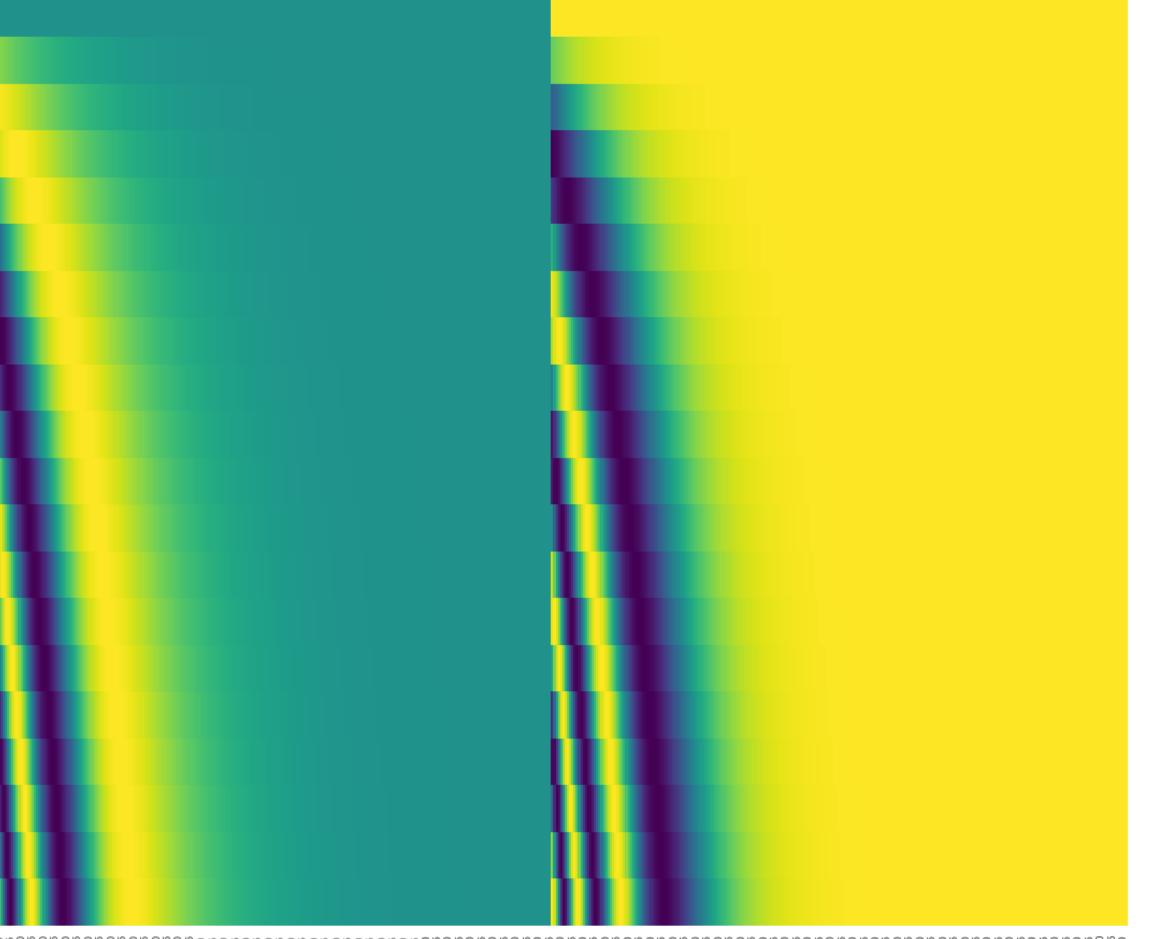




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$$x_i = E_{w_i} + P_i$$



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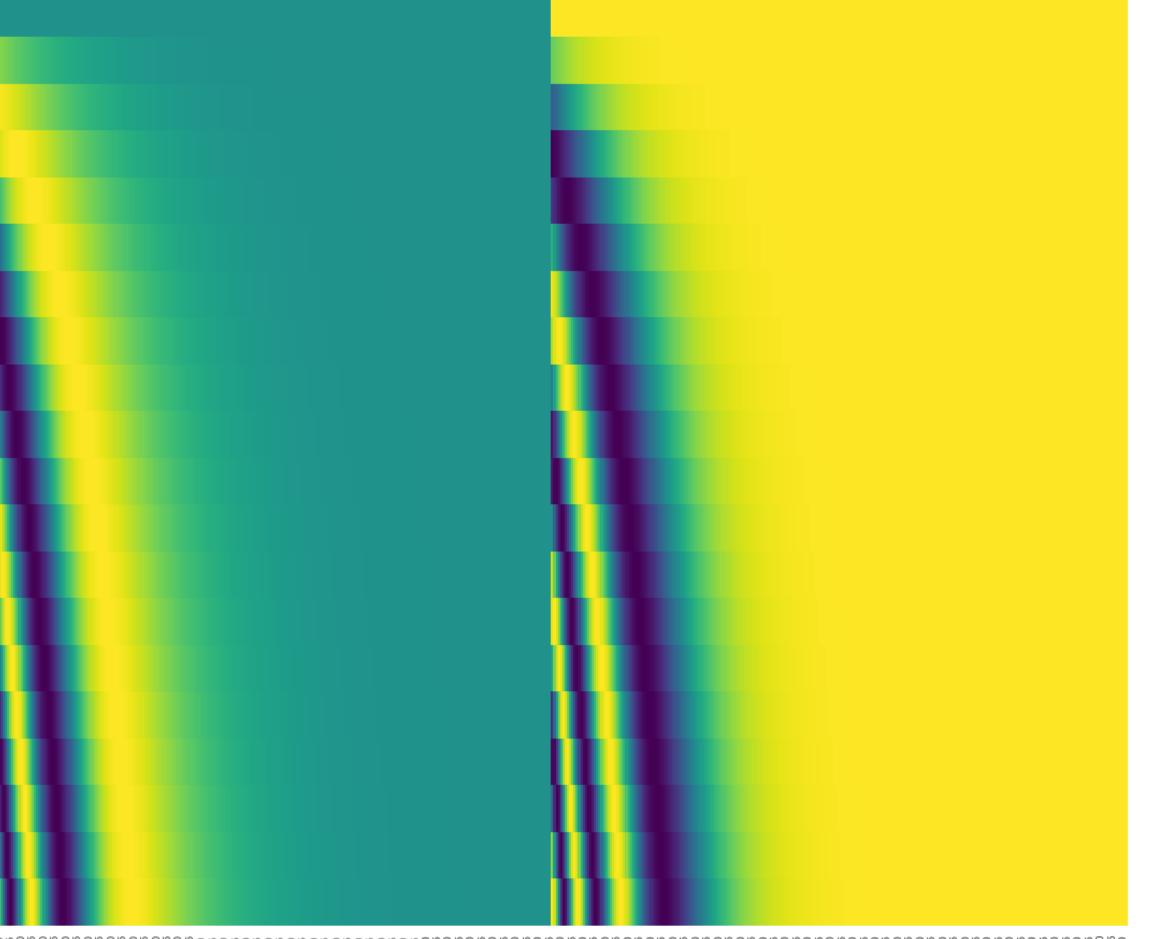


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• Can be fixed/pre-defined [see right] or entirely learned



 $\begin{array}{c} 0 & 0 \\ 0 & 0$











Fixed vs Learned Positional Encoding

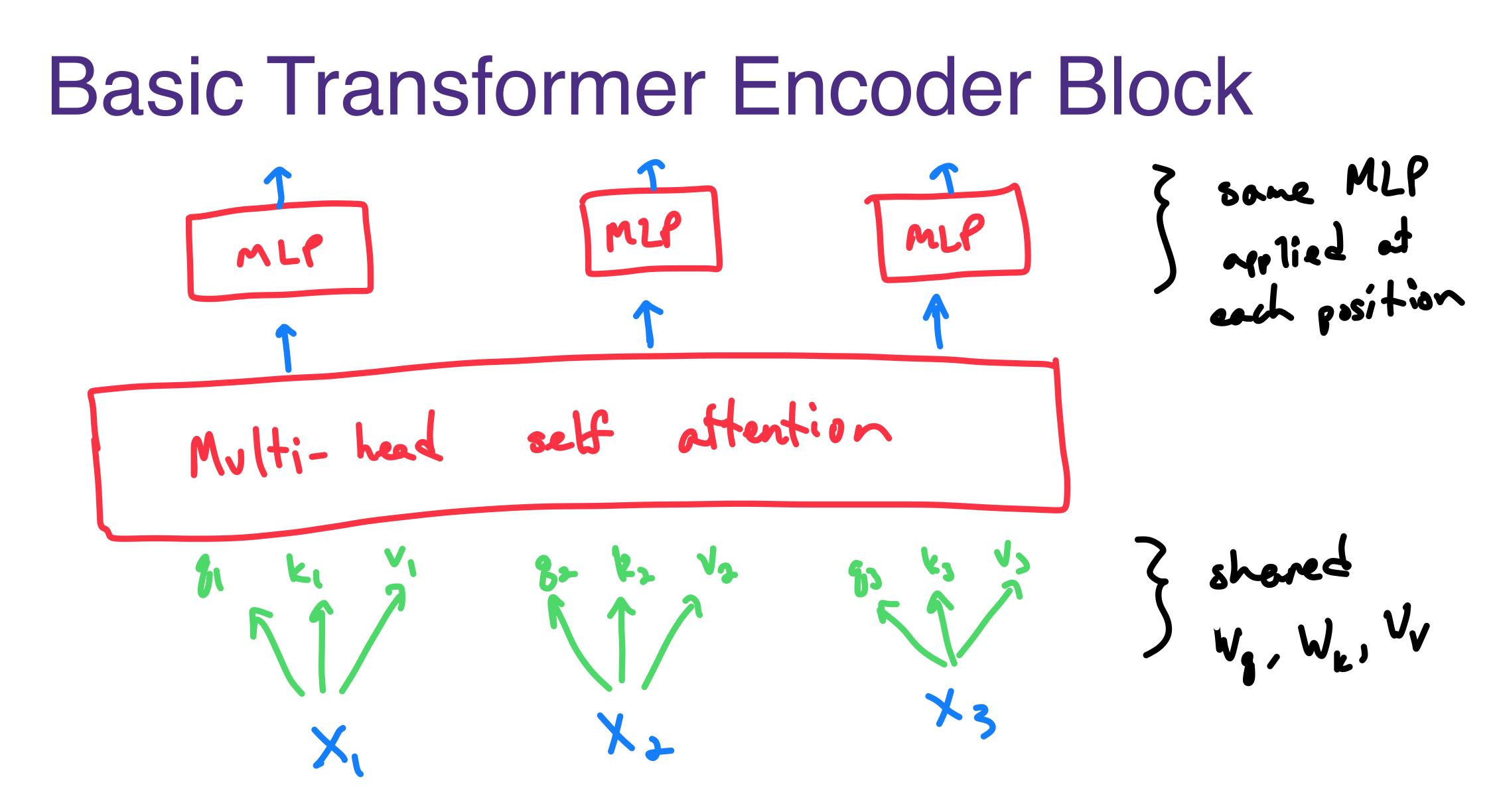
- Fixed:
 - No need to be learned
 - Guaranteed to be unique to position
 - Generalizes to longer sequence lengths (in theory at least)
- Learned:
 - Might learn more useful encodings of position than e.g. sinusoidal
 - Can't extrapolate to longer sequence lengths
 - [This has become the default/norm]
- distance, fixed bias of distance (ALiBi)

• Fancier ways of representing positional info: rotary embeddings, learned bias of







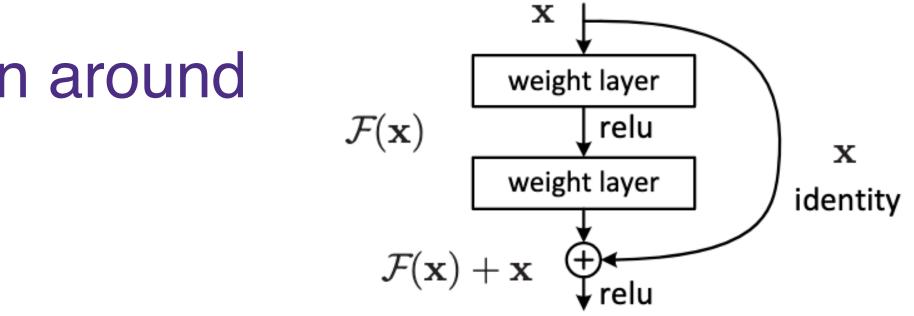


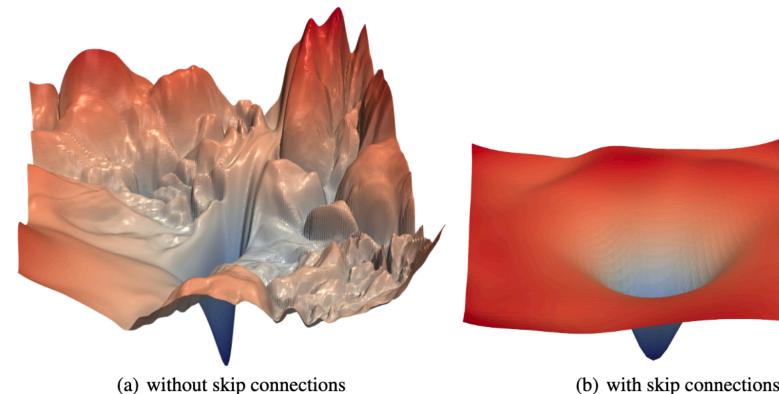




Final Ingredients: <u>Residual Connections</u>

- Core idea: add a "skip" connection around neural building blocks
- Replace f(x) with x + f(x)
- Makes training work much better, by smoothing out loss surface
- In Transformer: residual connection around both self-attention and feed-forward blocks
- Used widely now: FFNNs, CNNs, RNNs, Transformers, ...





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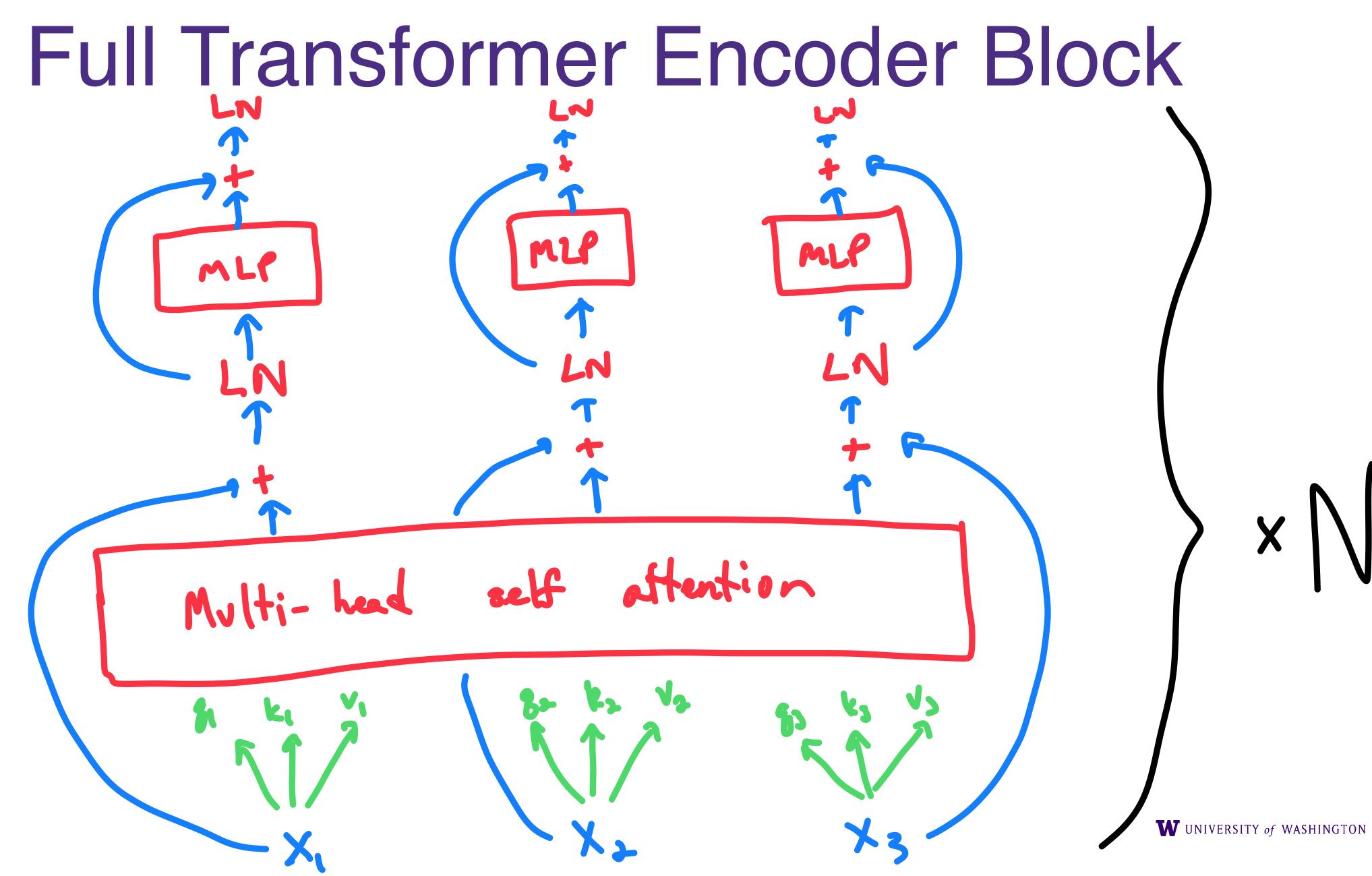
Final Ingredients: Layer Normalization

- Normalizing inputs: subtract mean, divide by standard deviation
 - Makes new mean 0, new standard deviation 1
 - Widely used in many kinds of statistical modeling [e.g. predictors in linear regression], including in NNs
- Layer norm: to each row x of a matrix [a batch]: $LN(x) = \frac{x \mu}{\sigma + \epsilon} \gamma + \beta$
 - Where μ is mean, σ is std dev
 - γ, β are learned scaling parameters [but often omitted entirely]















Initial WMT Results

Model ByteNet [15] Deep-Att + PosUnk [32] GNMT + RL [31] ConvS2S [8] MoE [26] Deep-Att + PosUnk Ensemble [32] GNMT + RL Ensemble [31] ConvS2S Ensemble [8] Transformer (base model) Transformer (big)

-

			-
BLEU		Training Cost (FLOPs)	
EN-DE	EN-FR	EN-DE	EN-FR
23.75			
	39.2		$1.0\cdot 10^{20}$
24.6	39.92	$2.3\cdot 10^{19}$	$1.4\cdot 10^{20}$
25.16	40.46	$9.6\cdot 10^{18}$	$1.5\cdot 10^{20}$
26.03	40.56	$2.0\cdot 10^{19}$	$1.2\cdot 10^{20}$
	40.4		$8.0\cdot10^{20}$
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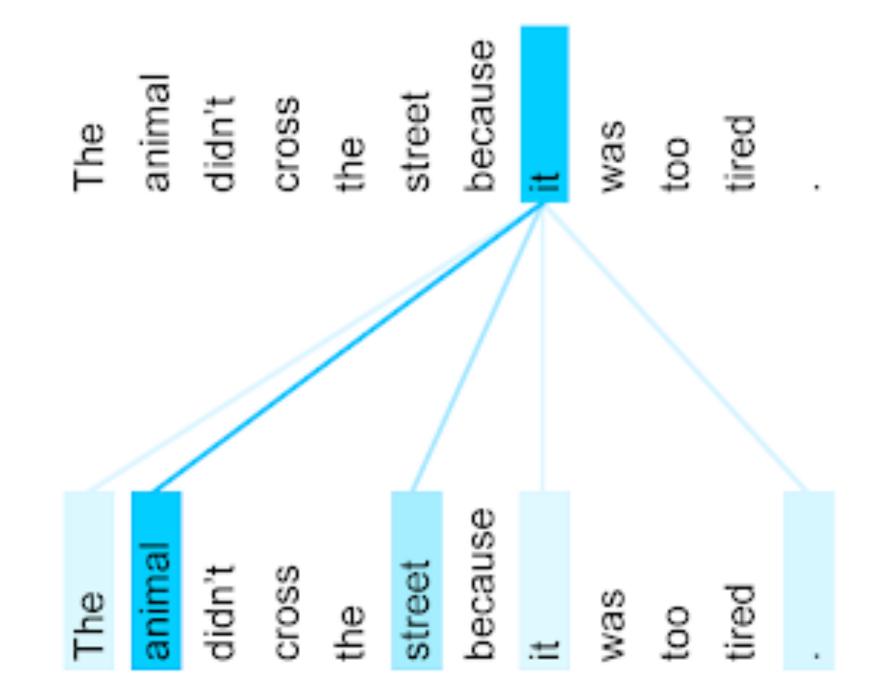
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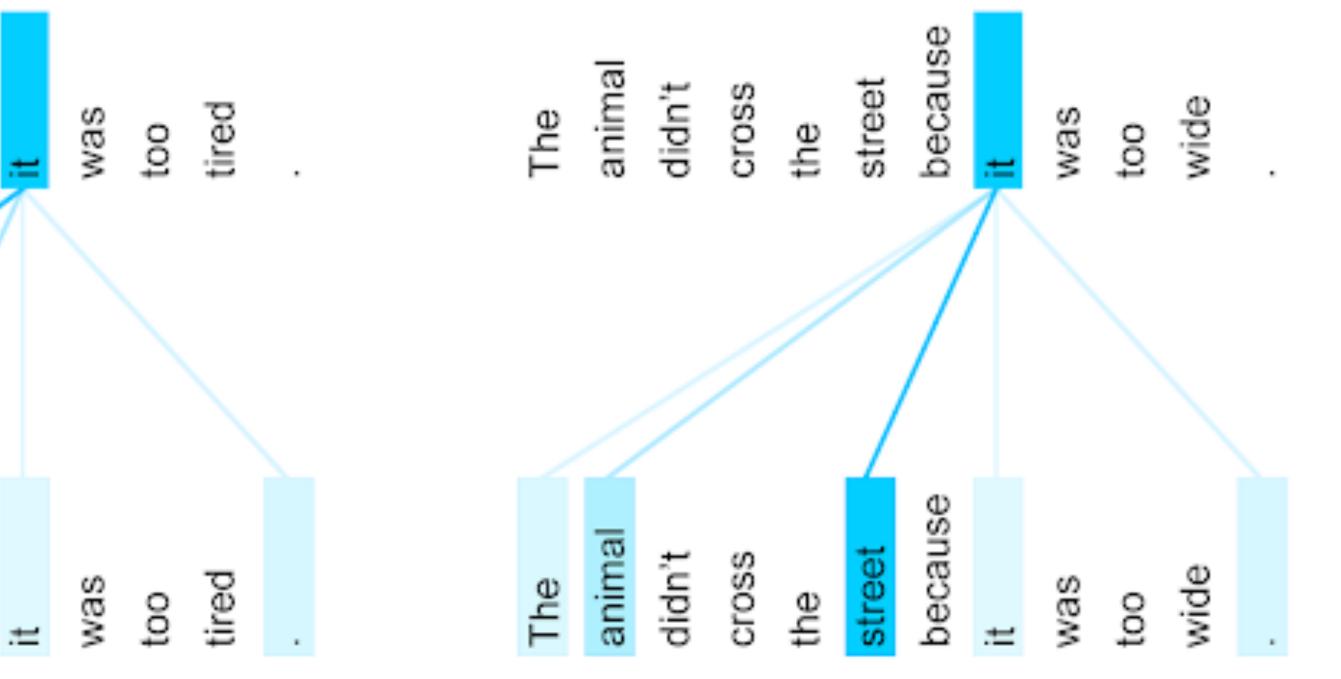
More on why important later





Attention Visualization: Coreference?



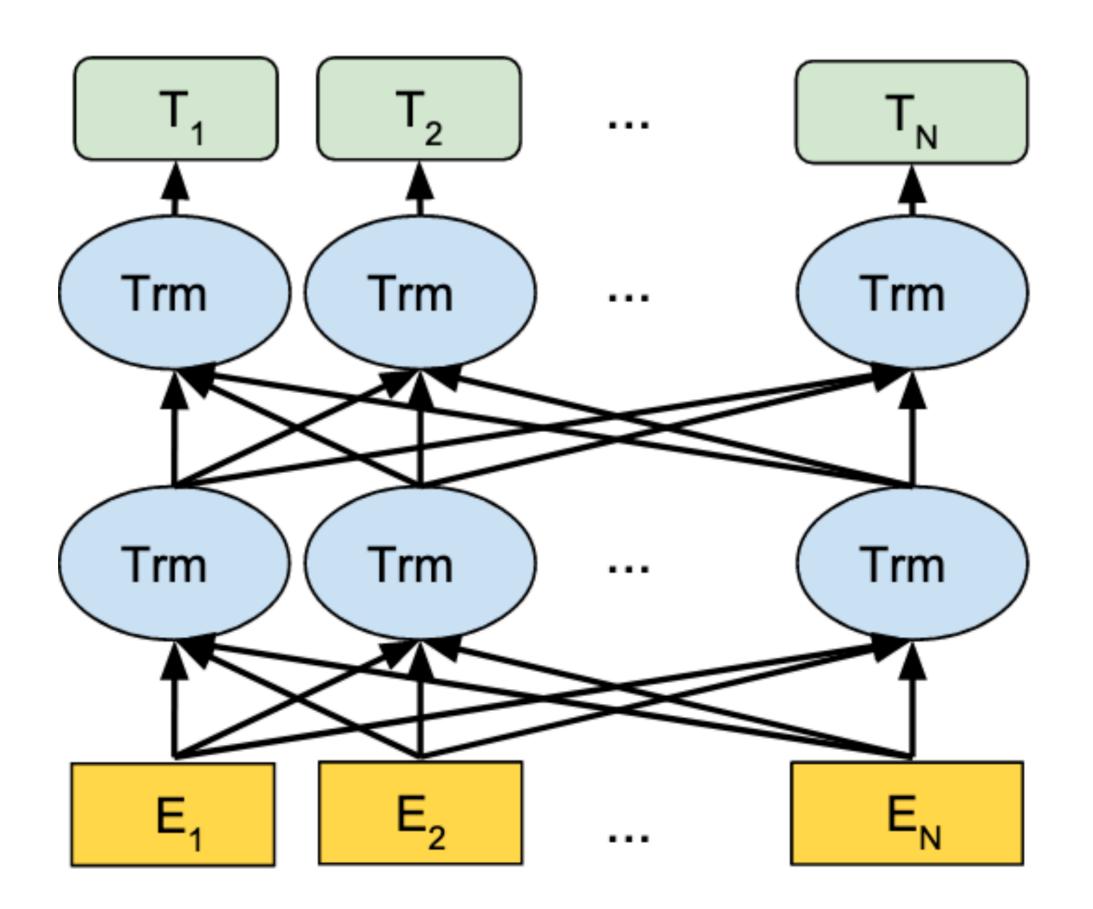


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Transformer: Path Lengths + Parallelism





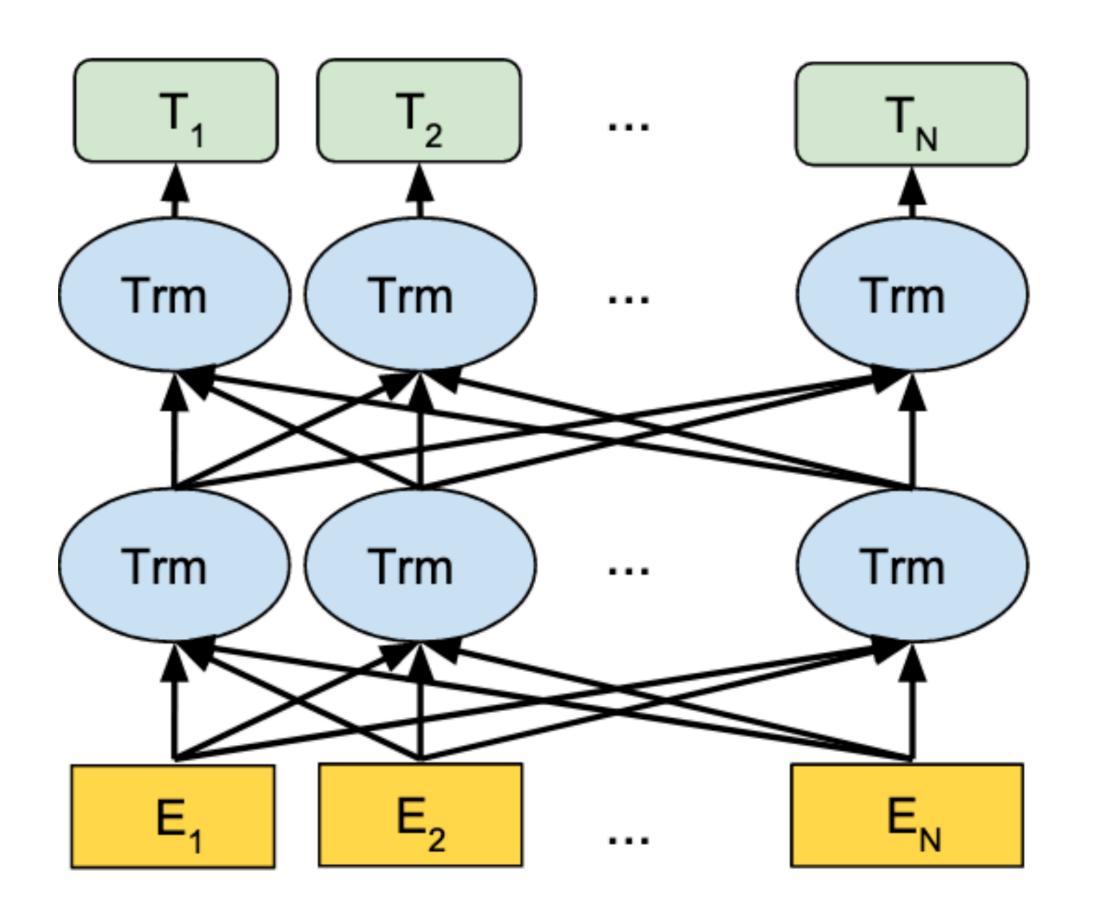








Transformer: Path Lengths + Parallelism





Path lengths between tokens: 1 [constant, not linear]









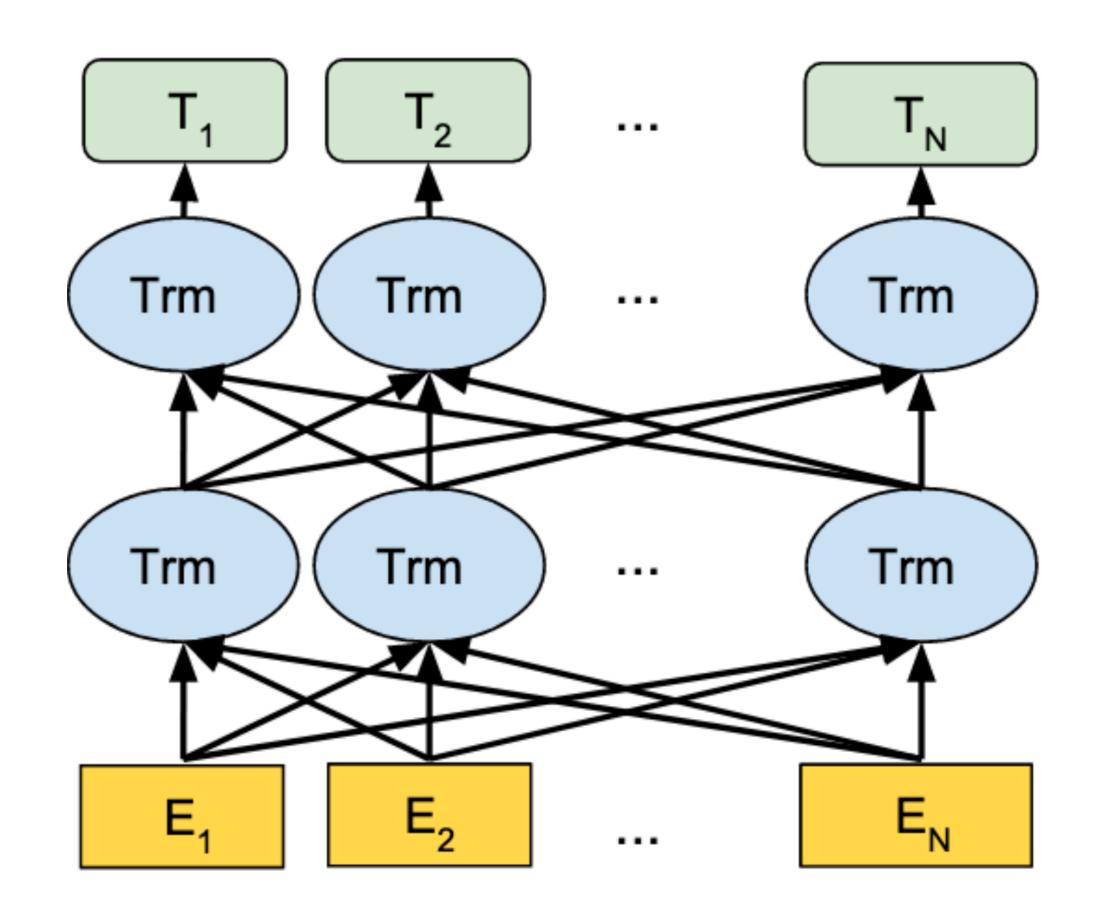


Transformer: Path Lengths + Parallelism

Computation order: Entire second layer: 1

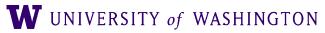
Entire first layer: 0

Also not linear in sequence length! Can be parallelized.



Path lengths between tokens: 1 [constant, not linear]













Transformer: Summary

- Entirely feed-forward
 - Therefore massively parallelizable
 - RNNs are inherently sequential, a parallelization bottleneck
- (Self-)attention everywhere
- Long-term dependencies:
 - LSTM: has to maintain representation of early item
 - Transformer: very short "path-lengths"









Next Time

- A deeper look at the *decoder* block of a Transformer
 - Attention masks
- Subword tokenization





